## programmable timer

## 1. An Overview

CD 4541B The programmable timer is composed of a 16-bit binary counter, a built-in oscillator (with an external capacitor and two resistors), an output control logic, and a special power-up reset circuit.

The particularity of the power reset circuit lies in: 1. There is no additional static current consumption; 2. This power reset function is valid in the entire voltage range $\left(3^{\sim} 15 \mathrm{~V}\right)$, whether allowed or prohibited.

If the power reset function is allowed, the internal timer and counter initialize when the power is on. The external reset pulse can also be initialized with the timer and counter when the power is already on. When the reset action is complete, the frequency of the built-in oscillator is determined by the external RC constant. The 16 -bit counter divides the frequency of the oscillator with the value of any 4-digit binary number.

## 2. Features

Order Available by frequency: $2^{8}, 2^{10}, 2^{13}$ Or $2^{16}$ 。
Make the counter add one on the positive edge of the clock transition.
Keep the built-in low-power RC oscillator ( $\pm 2 \%$ over the entire temperature range in a frequency range of less than 10 kHz

Precision, maintaining $\pm 10 \%$ accuracy and $\pm 3 \%$ process deviation accuracy in the entire operating power supply voltage range).

Order oscillator frequency range: DC ${ }^{\sim} 100 \mathrm{kHz}$.
Make the internal oscillator bypass when the external clock is used.
After the power supply increases, automatically reset and initialize all the counters.
Make the external master reset completely independent of the automatic reset operation.

Order can be used as a $2^{\mathrm{n}}$ Frequency divider or a single timer.
To flexibly change the output logic level by selecting $Q / Q$.

Order reset (automatic or master reset) places the oscillator in a forbidden state during the reset period, reducing the dynamic power consumption during this period.

Althe clock adjustment circuit to operate with extremely slow clock rise and down time.

Wide power supply voltage range: $3.0^{\sim} 15 \mathrm{~V}$.
Order 5V10V15V three gear parameter.
Make high noise tolerance- 0.45 VDD (tape p ).
The maximum input leakage current is $1 \mu \mathrm{~A}$ over the entire temperature range of 15 V .

## 3. Pipe pin diagram



## 4. Truth value table

| Pipe foot number | state |  |
| :---: | :---: | :---: |
|  | 0 | 1 |
| 5 | Automatic reset operation | Prohibit the automatic reset |
| 6 | Timer operation | master reset |
| 9 | After the reset, the output initial value is a low level | After the reset, the output initial value is a high level |
| 10 | Single cycle mode | Circulating mode |

## 5. Frequency division meter

| A | B | The N th counter level <br> of the data | 2 N value |
| :--- | :--- | :--- | :--- |
| 0 | 0 | 13 | 8192 |
| 0 | 1 | 10 | 1024 |
| 1 | 0 | 8 | 256 |
| 1 | 1 | 16 | 65536 |

## 6. Working characteristics

When the automatic reset pin is set to " 0 ", the counter circuit is initiated. Or when the power supply is switched on

When the main reset pin is set to " 1 " in time. Both reset all counters simultaneously, regardless of the original state of the counter.

Make the RC oscillator frequency determined by the external RC constant:

## $\mathrm{F}=1 /(2.3 \mathrm{RtcCtc})$ (frequency within 1 kHz f 100 kHz$)$

The selected value of $\operatorname{Rs}$ is $\operatorname{Rs}=2 \operatorname{Rtc}(\operatorname{Rs} 10 \mathrm{k} \Omega)$
Order the timing selection input (A and B) to provide A two-bit address to select the output of four count levels $\left(2^{8}, ~ 2^{10}, ~ 2^{13} 0 r 2^{16}\right)$ Any one of them. And 2 in the frequency division table ${ }^{n}$ Counts represent the $Q$ output of the N level of the counter. When A is " 1 " and B is " 1 ", 2 will be-selected ${ }^{16}$. When $A$ is " 1 " and $B$ is " 0 ", the normal count is interrupted and the level 9 of the counter jumps the previous level 8 counter to receive the clock directly from the oscillator (effective count is $2^{8}$ output).

Make the $\mathrm{Q} / \mathrm{Q}$ pins used to select the output level. When the counter is in the reset state, $\mathrm{Q} / \mathrm{Q}$ selects the pin to " 0 ", then Q output is " 0 "; $\mathrm{Q} / \mathrm{Q}$ selects the pin to " 1 ", then $Q$ output is " 1 ".

When the mode control pin (Pin 10) is set to " 1 ", the selected count value is continuously transmitted to the output. When the mode control

The pipe pin is set to " 0 ", and after the reset state, the RS trigger reset (see logical block diagram), the start row count, count to $2^{\text {n1 }}$ Later, the RS trigger is positioned and causes a change in the output state. Therefore, each count over $2^{n 1}$ After the number, you change the state of the output once. Therefore, a master reset pulse must be applied or the level of the mode control pin changed to reset the single-cycle operation.


Oscillator circuit uses a RC configuration diagram

## 7. Logical block diagram



## 8. Limit parameters

| symbol | parameter | condition | numeric <br> value | unit |
| :---: | :---: | :---: | :---: | :---: |
| v DD | Power voltage range |  | $-0.5^{\sim}+18$ | V |
| V in | input voltage range |  | $-0.5{ }^{\sim} \mathrm{VDD}+0.5$ | V |
| T stg | Package work, temperature range |  | $-65^{\sim} 150$ | ${ }^{\circ} \mathrm{C}$ |
| P D | Maximum power dissipation | DI P | 700 | m W |
|  |  | C 0B | 500 |  |
| T L | Point welding temperature |  | 260 | ${ }^{\circ} \mathrm{C}$ |

## 9. Recommended working conditions

| symbol | parameter | condition | numeric <br> value | unit |
| :--- | :--- | :--- | :--- | :--- |
| VD D | Power voltage range |  | $3^{\sim} 15$ | V |
| VI N | input voltage range |  | $0^{\sim}$ VDD | V |
|  | operating temperature <br> range |  | $-40^{\sim} 85$ | ${ }^{\circ} \mathrm{C}$ |

## remarks:

The working condition of the limit parameter exceeds the range to ensure the normal operation of the device. Devices can not be guaranteed under the limiting parameters
job security. Users are advised to use the device according to the working conditions recommended in the electrical parameter table.

Order Unless otherwise specified, VSS = 0 V.

## 10., and the electrical parameters

(Reference Voltage: Vss)

| paramete <br> r | symbol | condition | V DD | $-40^{\circ} \mathrm{C}$ |  | $25^{\circ} \mathrm{C}$ |  |  | $+85^{\circ} \mathrm{C}$ |  | unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | minimu <br> m | maximum | minimu $\mathrm{m}$ | typical case | maximum | minimu $\mathrm{m}$ | maximum |  |
| quiescent <br> current | IDD | VIN $=$ either VDD or VSS | 5.0 |  | 20 |  | 0. 005 | 20 |  | 150 | $\mu \mathrm{A}$ |
|  |  | VIN $=$ either <br> VDD or VSS | 10 |  | 40 |  | 0. 010 | 40 |  | 300 |  |
|  |  | $\begin{aligned} & \text { VIN = either } \\ & \text { VDD or VSS } \end{aligned}$ | 15 |  | 80 |  | 0.015 | 80 |  | 600 |  |
| Output low | V 0L |  | 5.0 |  | 0.05 |  | 0 | 0.05 |  | 0.05 | V |
|  |  | IO $<1 \mathrm{uA}$ | 10 |  | 0. 05 |  | 0 | 0.05 |  | 0. 05 |  |
| power |  |  | 15 |  | 0. 05 |  | 0 | 0. 05 |  | 0. 05 |  |
| Output high | V OH |  | 5.0 | 4. 95 |  | 4. 95 | 5 |  | 4. 95 |  | V |
| electricity |  | IO $<1 \mathrm{uA}$ | 10 | 9. 95 |  | 9. 95 | 10 |  | 9. 95 |  |  |
|  |  |  | 15 | 14. 95 |  | 14.95 | 15 |  | 14.95 |  |  |
| Input low | V 0L | $\begin{aligned} & .5 \mathrm{VO}=4 \text { or } \\ & 0.5 \mathrm{~V} \end{aligned}$ | 5.0 |  | 1.5 |  | 2 | 1. 5 |  | 1. 5 | V |
| power <br> flat |  | $\begin{aligned} & .0 \mathrm{VO}=9 \text { or } \\ & \text { 1. } 0 \mathrm{~V} \end{aligned}$ | 10 |  | 3.0 |  | 4 | 3.0 |  | 3.0 |  |
|  |  | $\begin{aligned} & \mathrm{V} 0=13.5 \text { or } \\ & 1.5 \mathrm{~V} \end{aligned}$ | 15 |  | 4. 0 |  | 6 | 4. 0 |  | 4. 0 |  |
| Enter high | V OH | $\begin{aligned} & .5 \mathrm{~V} 0=4 \text { or } \\ & 0.5 \mathrm{~V} \end{aligned}$ | 5.0 | 3.5 |  | 3.5 | 3 |  | 3.5 |  | V |
| powerflat |  | $\begin{aligned} & .0 \mathrm{VO}=9 \text { or } \\ & \text { 1. } 0 \mathrm{~V} \end{aligned}$ | 10 | 7.0 |  | 7.0 | 6 |  | 7. 0 |  |  |
|  |  | $\begin{aligned} & \mathrm{V} 0=13.5 \text { or } \\ & 1.5 \mathrm{~V} \end{aligned}$ | 15 | 11 |  | 11 | 9 |  | 11 |  |  |
| Low level | IOL | VOL $=0.4$ | 5.0 | 1. 70 |  | 1. 30 | 2.0 |  | 1. 10 |  | mA |
|  |  | VOL $=0.5 \mathrm{~V}$ | 10 | 2. 40 |  | 2. 20 | 5.0 |  | 2. 00 |  |  |
| loss |  | $\mathrm{V} 0 \mathrm{~L}=1.5 \mathrm{~V}$ | 15 | 9. 70 |  | 8. 50 | 15.0 |  | 6. 50 |  |  |
| High level | IOH | $\mathrm{VOH}=2.5 \mathrm{~V}$ | 5.0 | 5.1 |  | 3.20 | 6. 80 |  | 2. 90 |  | mA |
|  |  | $\mathrm{VOH}=9.5 \mathrm{~V}$ | 10 | 3. 80 |  | 3.50 | 5. 80 |  | 2. 85 |  |  |
| loss |  | $\mathrm{VOH}=13.5 \mathrm{~V}$ | 15 | 8.5 |  | 7.0 | 16.0 |  | 6. 22 |  |  |
| The current |  | $\mathrm{VIN}=0 \mathrm{~V}$ | 15 |  | -0.3 |  | $-10^{-5}$ | -0.3 |  | -1.0 |  |

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| input <br> currenton | IIN | VIN $=15 \mathrm{~V}$ 15$\quad$ | 3.0 |  | $10^{-5}$ | 0.3 |  | 1.0 | $\mu \mathrm{~A}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

*: IOH and IOL are results by testing one output.

## 11. Dynamic electrical parameters

$\left(\mathrm{TA}=25^{\circ} \mathrm{C}\right)$

| symbol | project | condition | V DD | least value | represe ntative value | crest value | unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| tTLH | Output rise time |  | 5 V |  | 50 | 200 | n s |
|  |  |  | 10 V |  | 30 | 100 |  |
|  |  |  | 15 V |  | 25 | 80 |  |
| tTHL | Output drop time |  | 5 V |  | 50 | 200 | ns |
|  |  |  | 10V |  | 30 | 100 |  |
|  |  |  | 15 V |  | 25 | 80 |  |
| $\begin{aligned} & \text { t PLH } \\ & \text { t PHL } \end{aligned}$ | propagation delay <br> time | Power off, on transmission delay from clock to Q | 5 V |  | 1.8 | 4.0 | n s |
|  |  |  | 10V |  | 0.6 | 1.5 |  |
|  |  |  | 15 V |  | 0.4 | 1.0 |  |
| $\begin{aligned} & \text { t PHL } \\ & \text { t PLH } \end{aligned}$ | propagation delay <br> time | Transmission delay of power on and off, from clock to Q | 5 V |  | 3.2 | 8.0 | n s |
|  |  |  | 10 V |  | 1.5 | 3.0 |  |
|  |  |  | 15 V |  | 1.0 | 2.0 |  |
| t WH | clock-pulse width |  | 5 V | 400 | 200 |  | ns |
|  |  |  | 10 V | 200 | 100 |  |  |
|  |  |  | 15 V | 150 | 70 |  |  |
| tcl | clock frequency |  | 5 V |  | 2.5 | 1.0 | M Hz |
|  |  |  | 10V |  | 6.0 | 3.0 |  |
|  |  |  | 15 V |  | 8.5 | 4.0 |  |
| t WH | MR pulse length |  | 5 V | 400 | 170 |  | ns |
|  |  |  | 10V | 200 | 75 |  |  |
|  |  |  | 15 V | 150 | 50 |  |  |
| C I | Average input capacitor | Any input |  |  | 5.0 | 7.5 | pF |
| CPD | Power supply power consumption capacitance |  |  |  | 100 |  | pF |

remarks:

1. The $A C$ parameters are guaranteed by the relevant $D C$ parameters.
2. CPD represents the dynamic power consumption of each CMO S device with no load.

## 12. Test circuit and waveform graph

Make the power consumption test circuit and waveform diagram

( $R_{4 c}$ and $C_{\mathrm{ic}}$ outputs are left open)


Make the switch time test circuit and the waveform diagram


## 13. Package size diagram

Make the DIP 14 package form


Make the SOP 14 package form


