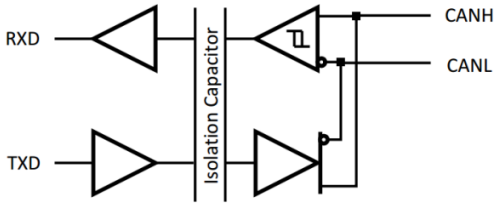
FEATURES

- Fully compatible with the ISO 11898 standard
- Thermally protected
- High CMTI: 100 kV/μs
- Transmit Data (TXD) dominant time-out function
- Bus fault protection of -40V to +40V
- Input levels compatible with 3.3 V and 5 V devices
- Low loop delay: 150ns（Typical） 210ns（Max)
- At least 110 nodes can be connected
- High speed (up to 1 MBaud)
- High system level EMC performance
- packages: DUB8， SOPW8 V_{ISO}=2500 V_{RMS}
  SOPW16, V_{ISO}=5000 V_{RMS}

FUNCTION DIAGRAM



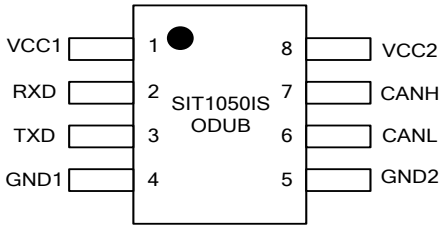
Function schematic

DESCRIPTIO

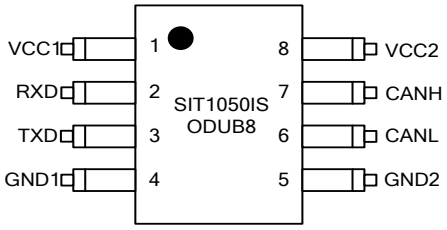
SIT1050ISO is a capacitively isolated CAN transponder, which complies with the technical specifications of the ISO11898 standard. It contains multiple logic input and output buffers separated by silicon dioxide (SiO2) insulation barriers. The device provides differential transmit capability to the bus and differential receive capability to the CAN controller.

PARAMETER	SYMBOL	CONDITION	MIN.	MAX.	UNIT
WB DUB8，SOPW8 Withstand isolation voltage	V_{ISO}		2500 typ		V_{RMS}
WB SOPW16 Withstand isolation voltage	V_{ISO}		5000 typ		V_{RMS}
Common-Mode Transients	CMTI		50	100	kV/μs
Supply voltage	V_{cc}		4.5	5.5	V
Maximum transmission rate	$1/t_{bit}$	Non-return to zero code	1		Mbaud
CANH/CANL input or output voltage	V_{can}		-40	+40	V
Bus differential voltage	V_{diff}		1.5	3.0	V
Virtual junction temperature	T_{amb}		-40	125	℃

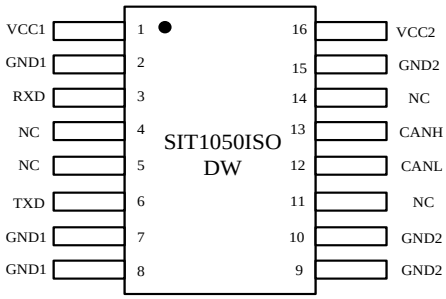
PIN CONFIGURATION



SOPW8



DUB8



SOPW16

LIMITING VALUES

PARAMETER	SYMBOL	VALUE	UNIT
Supply voltage	V_{CC1}, V_{CC2}	-0.5~+6.5	V
TXD voltage		-0.5~V_{CC1}+0.5	V
Voltage range at any bus terminal	CANL，CANH	-40~40	V
Transient voltage on pins CANH, CANL see Fig.7	V_{tr}	-200~+200	V
Storage temperature		-40~150	℃
Virtual junction temperature		-40~125	℃
Welding temperature range		300	℃

The maximum limit parameters means that exceeding these values may cause irreversible damage to the device. Under these conditions, it is not conducive to the normal operation of the device. The continuous operation of the device at the maximum allowable rating may affect the reliability of the device. The reference point for all voltages is ground.

PINNING

DUB8,SOPW8 PIN	SYMBOL	DESCRIPTION
1	V_{CC1}	Power Supply for Logic Side，range 3.0V~5.5V
2	RXD	receive data output
3	TXD	transmit data input
4	GND1	Ground 1, the ground reference for Isolator Logic Side
5	GND2	Ground 2, the ground reference for Isolator Bus Side
6	CANL	LOW-level CAN bus line
7	CANH	HIGH-level CAN bus line
8	V_{CC2}	Power supply for Bus Side，range 4.5V~5.5V

SOPW16 PIN	SYMBOL	DESCRIPTION
1	VCC1	Power Supply for Logic Side，range 3.0V~5.5V
2	GND1	Ground 1, the ground reference for Isolator Logic Side
3	RXD	receive data output
4	NC	No Connection
5	NC	No Connection
6	TXD	transmit data input
7	GND1	Ground 1, the ground reference for Isolator Logic Side
8	GND1	Ground 1, the ground reference for Isolator Logic Side
9	GND2	Ground 2, the ground reference for Isolator Bus Side
10	GND2	Ground 2, the ground reference for Isolator Bus Side
11	NC	No Connection
12	CANL	LOW-level CAN bus line

13	CANH	HIGH-level CAN bus line
14	NC	No Connection
15	GND2	Ground 2, the ground reference for Isolator Bus Side
16	V_{CC2}	Power supply for Bus Side， range 4.5V~5.5V

DRIVER ELECTRICAL CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
CANH dominant output voltage	$V_{OH(D)}$	VI=0V，RL=60Ω，Fig 1、Fig .2	2.9	3.4	4.5	V
CANL dominant output voltage	$V_{OL(D)}$		0.8		1.5	V
Bus recessive output voltage	$V_{O(R)}$	VI=3V，RL=60Ω，Fig 1、Fig .2	2	2.5	3	V
Bus dominant differential output voltage	$V_{OD(D)}$	VI=0V，RL=60Ω，Fig 1、Fig .2	1.5		3	V
Bus recessive differential output voltage	$V_{OD(R)}$	VI=3V Fig 1、Fig .2	-0.012		0.012	V
		VI=3V NO LOAD	-0.5		0.05	V
Transmitter dominant voltage symmetry	$V_{dom(TX)sym}$	$V_{dom(TX)sym}=V_{CC}-V_{CANH}-V_{CANL}$	-400		400	mV
Transmitter voltage symmetry	V_{TXsym}	$V_{TXsym}=V_{CANH}+V_{CANL}$	$0.9V_{CC}$		$1.1V_{CC}$	V
Common-mode output voltage	V_{OC}	Fig.8	2	2.5	3	V
Peak-to-peak Common-mode output voltage	$\triangle V_{OC}$			30		mV
Short-circuit output current	I_{OS}	CANH=-12V，CANL=open，Fig.11	-105	-72		mA
		CANH=12V，CANL=open，Fig.11		0.36	1	mA

		CANL=-12V，CANH=open，Fig.11	-1	0.5		mA
		CANL=12V，CANH=open，Fig.11		71	105	mA
Recessive output current	$I_{O(R)}$	-27V<CANH<32V 0<VCC<5.25V	-2.0		2.5	mA
Common-Mode Transients	CMTI	Fig.12	±50		±100	kV/μs

（V_{CC1}=V_{CC2}=5V±10% ,Temp=T_{MIN}~T_{MAX}， typical in V_{CC1}=V_{CC2}=+5V， Temp＝25℃）

DRIVER SWITCHING CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Propagation delay time,low-to-high-level output	tPLH	Fig.4	31	65	120	ns
Propagation delay time,low-to-high-level output	tPHL		25	45	90	ns
Differential output signal rise time	tr			25		ns
Differential output signal fall time	tf			50		ns
Bus dominant time-out time	t_{dom}	Fig.10	300	450	700	μs

（V_{CC1}=V_{CC2}=5V±10% ,Temp=T_{MIN}~T_{MAX}， typical in V_{CC1}=V_{CC2}=+5V， Temp＝25℃）

RECEIVER ELECTRICAL CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Positive-going input threshold voltage	V_{IT+}	Fig.5		800	900	mV
Negative-going input threshold voltage	V_{IT-}		500	650		mV
Hysteresis voltage (VIT+ – VIT–)	V_{HYS}		100	125		mV

High-level output voltage	V_{OH}	IO=-2mA，Fig.6	4	4.6		V
Low-level output voltage	V_{OL}	IO=2mA，Fig.6		0.2	0.4	V
Power-off bus input current	$I_{(OFF)}$	CANH or CANL=5V，Other pin=0V		165	250	μA
Input capacitance to ground, (CANH or CANL)	C_I			13		pF
Differential input capacitance	C_{ID}			5		pF
Input resistance, (CANH or CANL)	R_{IN}	TXD=3V	15	30	40	KΩ
Differential input resistance	R_{ID}		30		80	KΩ
Input resistance matching	RI_{match}	CANH=CANL	-3%		3%	
The range of commen-mode voltage	V_{COM}		-12		12	V

（V_{CC1}=V_{CC2}=5V±10% ,Temp=T_{MIN}~T_{MAX}，typical in V_{CC1}=V_{CC2}=+5V，Temp＝25℃）

RECEIVER SWITCHING CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Propagation delay time,low-to-high-level output	tPLH	Fig.6	60	100	130	ns
Propagation delay time,low-to-high-level output	tPHL		45	70	105	ns
RXD signal rise time	tr			8		ns
RXD signal fall time	tf			8		ns

（V_{CC1}=V_{CC2}=5V±10% ,Temp=T_{MIN}~T_{MAX}，typical in V_{CC1}=V_{CC2}=+5V，Temp＝25℃）

DEVICE SWITCHING CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Loop delay1, driver input to receiver output, Recessive to Dominant	Td(LOOP1)	Fig.9	112		210	ns
Loop delay 2, driver input to receiver output, Dominant to Recessive	Td(LOOP2)		112		210	ns

（V_{CC1}=V_{CC2}=5V±10% ,Temp=T_{MIN}~T_{MAX}， typical in V_{CC1}=V_{CC2}=+5V， Temp＝25℃）

OVER TEMPERATURE PROTECTION

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Shutdown junction temperature	Tj(sd)			160		℃

SUPPLY CURRENT

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
V_{CC1} Supply current	I_{CC1}	V_I =0V or V_{CC1},V_{CC1} = 3.3V		1.8	2.8	mA
		V_I =0V or V_{CC1},V_{CC1} =5V		2.3	3.6	mA
V_{CC2} Supply current	I_{CC2}	V_I=0V LOAD=60Ω		50	70	mA
		V_I=VCC		6	10	mA

（V_{CC1}=V_{CC2}=5V±10% ,Temp=T_{MIN}~T_{MAX}， typical in V_{CC1}=V_{CC2}=+5V， Temp＝25℃）

FUNCTION TABLE

Table1.CAN TRANSCEIVER TRUTH TABLE

DRIVER				RECEIVER		
INPUTS	OUTPUTS		BUS STATE	CANH- CANL	RXD	BUS STATE
TXD	CANH	CANL				
L	H	L	Dominate	VID≥0.9V	L	Dominate
H	Z	Z	Recessive	0.5V<VID<0.9V	?	?
Open	Z	Z	Recessive	VID ≤ 0.5 V	H	Recessive
X	Z	Z	Recessive	Open	H	Recessive

（1）H=high level; L=low level; X=irrelevant

Table 2. DRIVER FUNCTION TABLE

INPUTS	OUTPUTS		Bus State
TXD(1)	CANH(1)	CANL(1)	
L	H	L	Dominate（显性）
H	Z	Z	Recessive（隐性）

（1）H=high level; L=low level; X=irrelevant; Z=high impedance

Table 3. RECEIVER FUNCTION TABLE

V_{ID}=CANH-CANL	V_{ID}=CANH-CANL	Bus State	Bus State
Normal or Silent	V_{ID}≥0.9V	Dominate（显性）	Dominate（显性）
	0.5< V_{ID}<0.9V	?	?
	V_{ID}≤0.5V	Recessive（隐性）	Recessive（隐性）
	Open (VID≈0V)	OPEN（隐性）	Recessive（隐性）

（1）H=high-level; L=low-level; ?=uncertain

TEST CIRCUIT

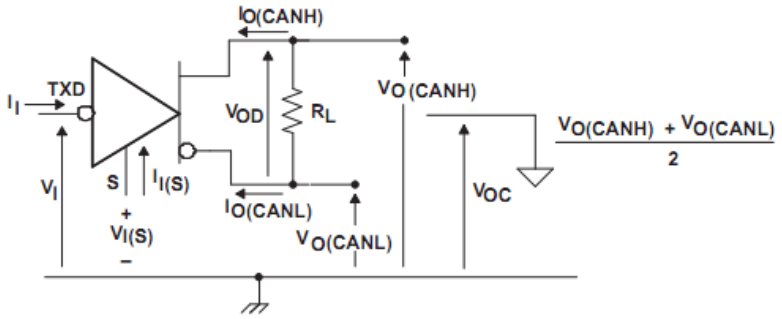


Fig.1 Driver Voltage, Current, and Test Definition

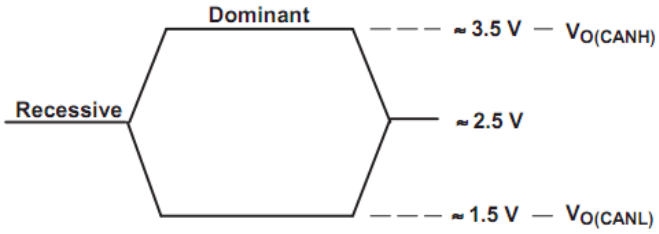


Fig.2 Bus Logic State Voltage Definition

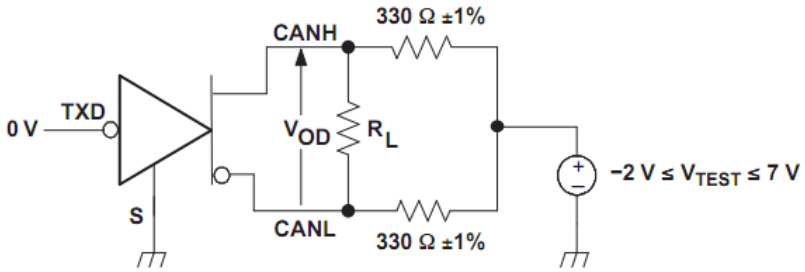


Fig.3 Driver V_{OD} Test Circuit

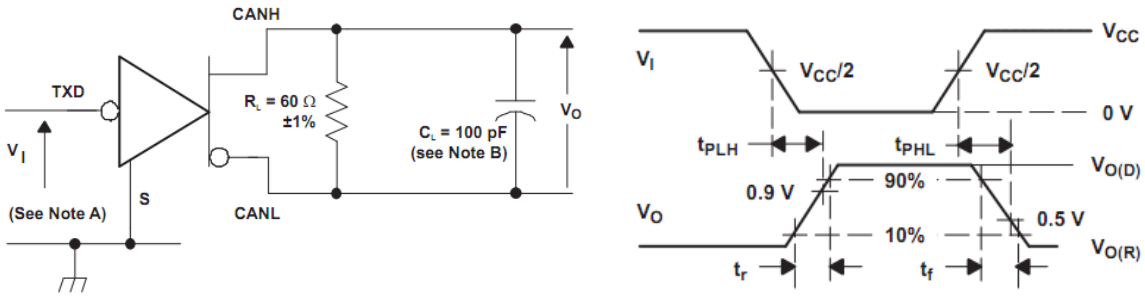


Fig.4 Driver Test Circuit and Waveform

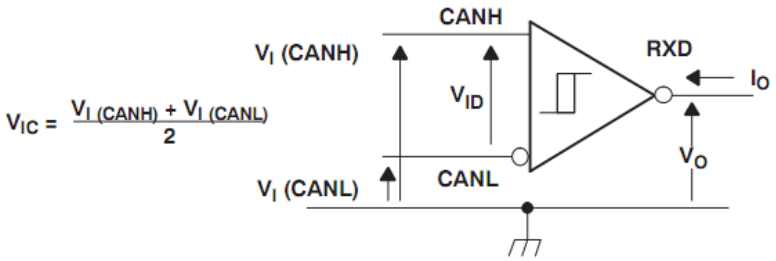
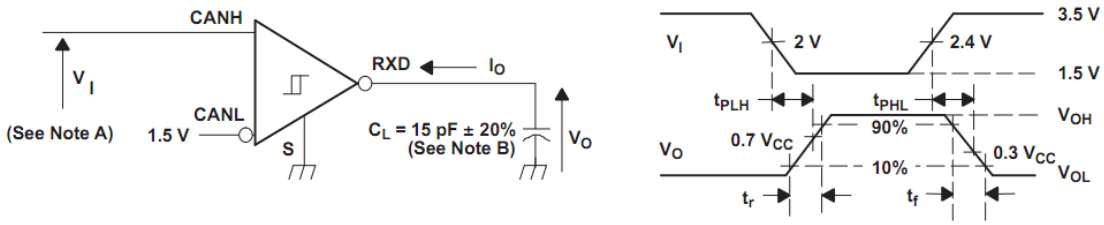


Fig.5 Receiver Voltage and Current Definition



A. The input pulse is supplied by a generator having the following characteristics: PRR ≤ 125 kHz, 50% duty cycle, t_r ≤ 6 ns, t_f ≤ 6ns, Z_O = 50 Ω.

B. C_L includes instrumentation and fixture capacitance within ±20%.

Fig.6 Receiver Test Circuit and Waveform

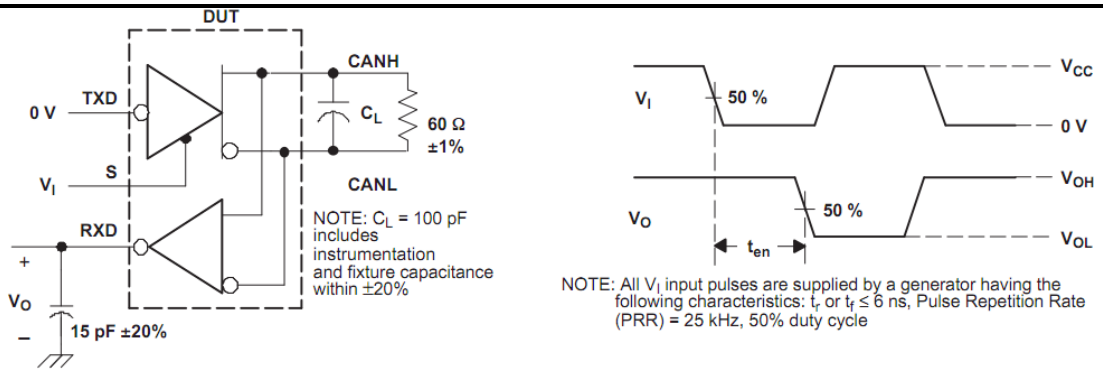
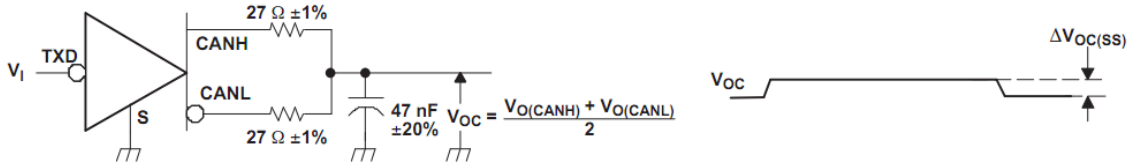


Fig.7 t_{EN} Test Circuit and Waveform



A. All VI input pulses are from 0 V to VCC and supplied by a generator having the following characteristics: tr or tf ≤ 6 ns. Pulse Repetition Rate (PRR) = 125 kHz, 50% duty cycle.

Fig.8 Peak-to-Peak Common Mode Output Voltage Test and Waveform

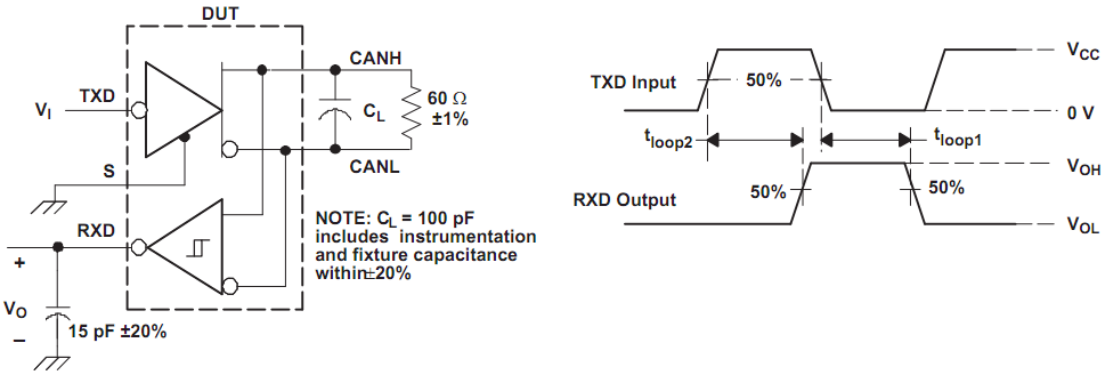


Fig.9 $t_{(LOOP)}$ Test Circuit and Waveform

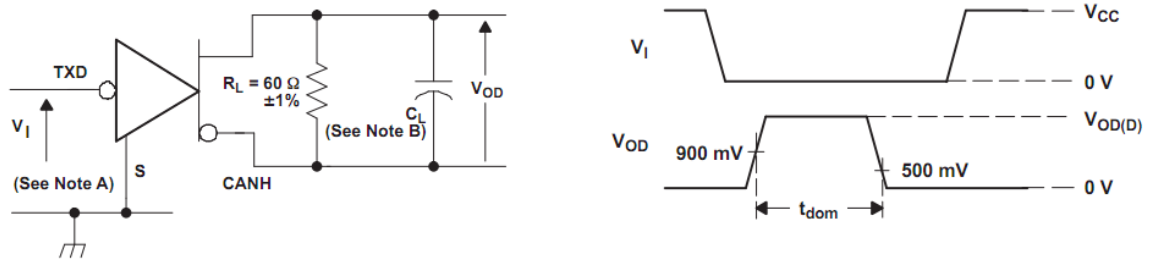


Fig.10 Dominant Time-Out Test Circuit and Waveform

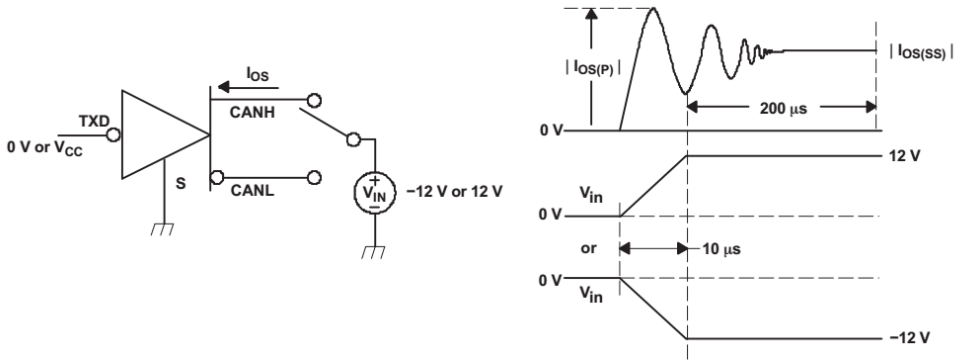


Fig.11 Driver Short-Circuit Current Test Circuit and Waveform

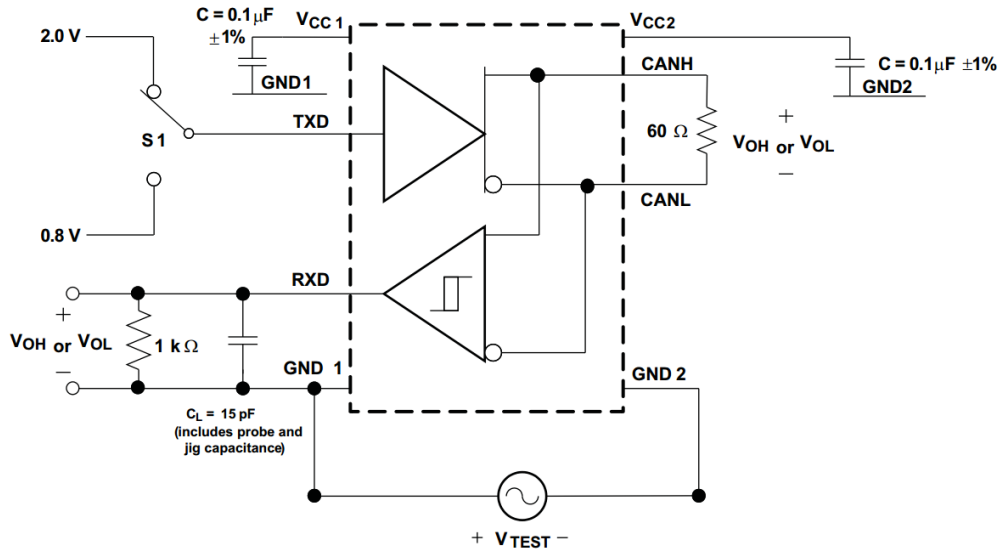


Fig.12 Common-Mode Transient Immunity Test Circuit

ADDIYIONAL DESCRIPTION

1 Sketch

SIT1050ISO is an interface chip with isolation function for CAN protocol controller and physical bus, and can be applied to the fields of trucks, buses, cars, industrial control etc. It is primarily intended for high speed applications, up to 1 MBaud, in passenger cars. The device provides differential transmit capability to the bus and differential receive capability to the CAN controller, and fully compatible with the ISO 11898 standard.

Provide wide body SOPW16 package, isolation withstand voltage 5000VRMS.

Provide wide-body DUB8, SOPW8 package, isolation withstand voltage 2500VRMS, Common-Mode Transients up to 100kV/μs.

2 Current protection

A current-limiting circuit protects the transmitter output stage from damage caused by accidental short-circuit to either positive or negative supply voltage, although power dissipation increases during this fault condition.

3 Over temperature protection

The output drivers are protected against over-temperature conditions. If the virtual junction temperature exceeds the shutdown junction temperature Tj(sd), the output drivers will be disabled until the virtual junction temperature becomes lower than Tj(sd) and TXD becomes recessive again.By including the TXD condition, the occurrence of output driver oscillation due to temperature drifts is avoided.

4 TXD dominant time-out function

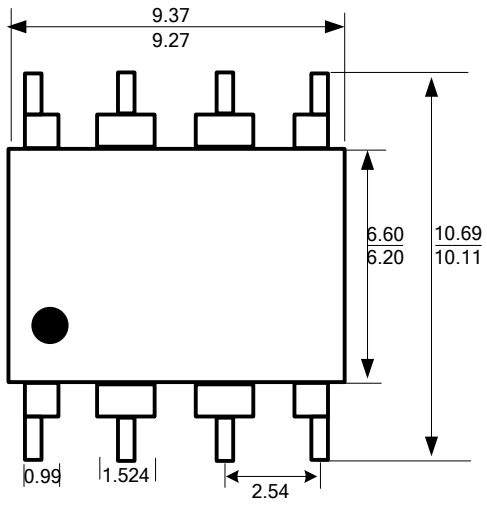
A ‘TXD dominant time-out’ timer circuit prevents the bus lines from being driven to a permanent dominant state(blocking all network communication) if pin TXD is forced permanently LOW by a hardware and/or software application failure. The timer is triggered by a negative edge on pin TXD.

If the duration of the LOW level on pin TXD exceeds the internal timer value (tdom), the transmitter is disabled, driving the bus lines into a recessive state. The timer is reset by a positive edge on pin TXD.

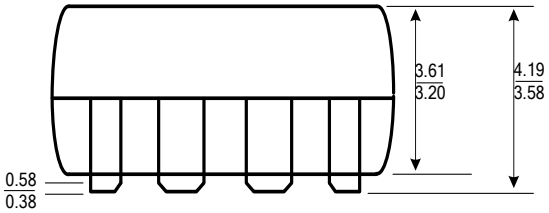
5 Operating mode

SIT1050ISO works in high-speed mode, which is the default working mode.

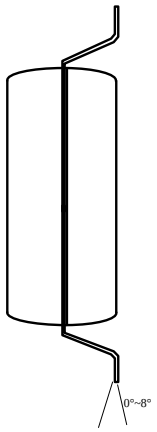
DUB8 DIMENSIONS



top view

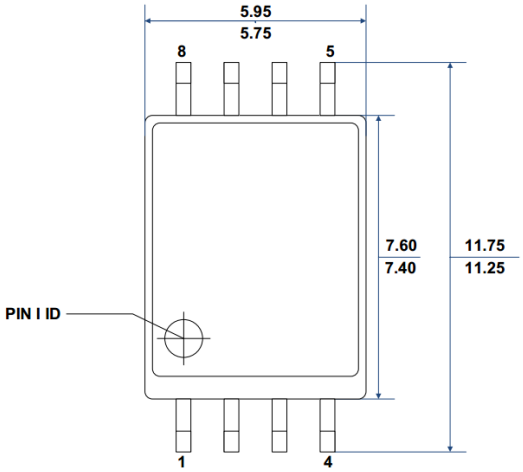


front view

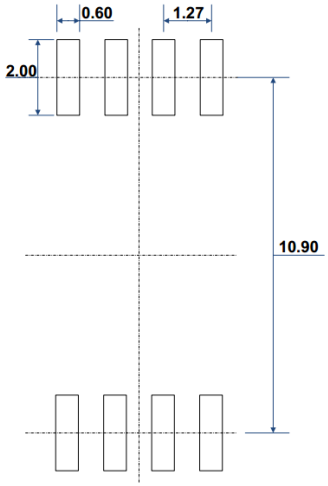


side view

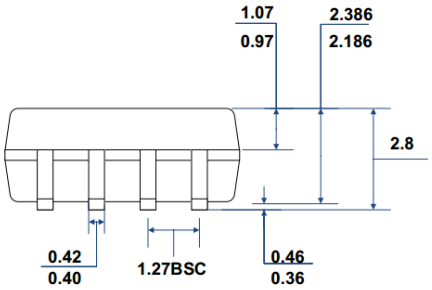
SOPW8 DIMENSIONS



top view



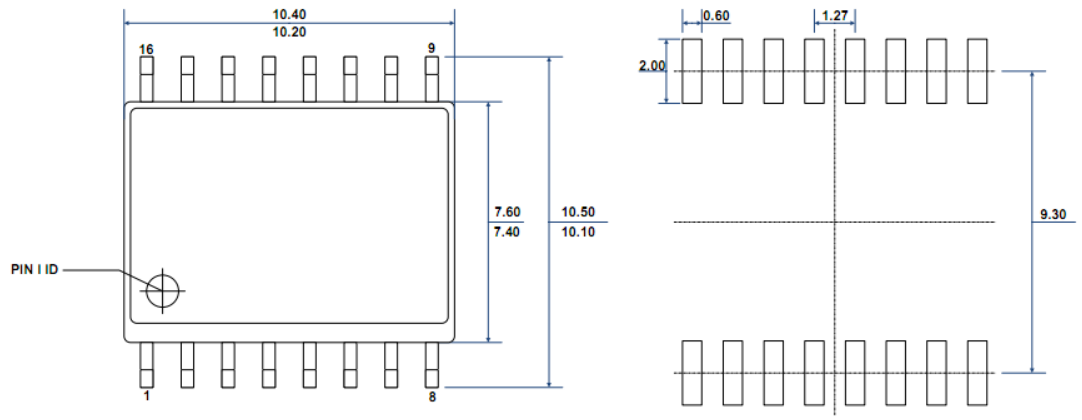
Recommended PCB Layout — Top Layer



front view

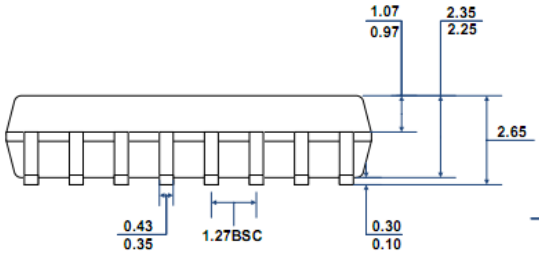
side view

SOPW16 DIMENSIONS



top view

Pin pitch



front view

side view

ORDERING INFORMATION

TYPE NUMBER	TEMPERATURE	PACKAGE
SIT1050ISODUB8	-40℃~125℃	DUB8
SIT1050ISODUB	-40℃~125℃	SOPW8
SIT1050ISODW	-40℃~125℃	SOPW16

DUB8 package is 800 pieces/disc.
SOPW8 package is 1000 pieces/disc.
SOPW16 package is 1000 pieces/disc.