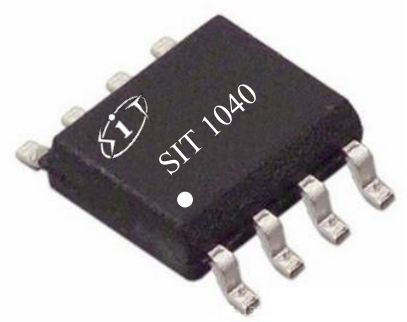
FEATURES

- Fully compatible with the ISO 11898 standard
- Thermally protected
- Input levels compatible with 3.3 V and 5 V devices
- Transmit Data (TXD) dominant time-out function
- Very low-current standby mode with remote wake-up Capability via the bus: 5μA Typical
- Transceiver in unpowered state disengages from the bus (zero load)
- At least 110 nodes can be connected
- High speed (up to 1 MBaud)
- Very low Electro Magnetic Emission (EME)

OUTLINE



Provide Green and Environmentally Friendly Lead-free package

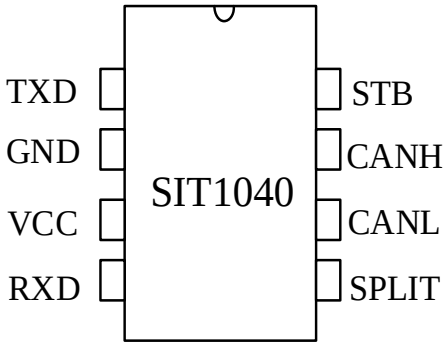
*Provide HVSON8 / DFN3*3-8，Small Outline， Leadless Package

DESCRIPTION

The SIT1040 is the interface between the Controller Area Network (CAN) protocol controller and the physical bus. It is primarily intended for high speed applications, up to 1 MBaud, in passenger cars. The device provides differential transmit capability to the bus and differential receive capability to the CAN controller.

PARAMETER	SYMBOL	CONDITION	MIN.	MAX.	UNIT
Supply voltage	V_{cc}		4.5	5.5	V
Maximum transmission rate	$1/t_{bit}$	Non-return to zero code	1		Mbaud
CANH/CANL input or output voltage	V_{can}		-40	+40	V
Bus differential voltage	V_{diff}		1.5	3.0	V
Virtual junction temperature	T_{amb}		-40	125	℃
ESD	Vesd	HBM	±8		KV

PIN CONFIGURATION



LIMITING VALUES

PARAMETER	SYMBOL	VALUE	UNIT
Supply voltage	V_{CC}	-0.3~+6	V
DC voltage on TXD/RXD/STB pins	TXD，RXD，STB	-0.3~VCC+0.3	V
Voltage range at any bus terminal (CANH, CANL, SPLIT)	CANL，CANH，SPLIT	-40~40	V
Transient voltage on pins CANH, CANL and SPLIT see Fig.7	V_{tr}	-200~+200	V
Storage temperature		-55~150	℃
Virtual junction temperature		-40~125	℃
Welding temperature range		300	℃

The maximum limit parameters means that exceeding these values may cause irreversible damage to the device. Under these conditions, it is not conducive to the normal opration of the device. The continuous operation of the device at the maximum allowable rating may affect the reliability of the device. The reference point for all voltages is ground.

PINNING

PIN	SYMBOL	DESCRIPTION
1	TXD	transmit data input
2	GND	ground supply
3	VCC	supply voltage
4	RXD	receive data output; reads out datafrom the bus lines
5	SPLIT	common-mode stabilization output
6	CANL	LOW-level CAN bus line
7	CANH	HIGH-level CAN bus line
8	STB	standby mode control input

DRIVER ELECTRICAL CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
CANH dominant output voltage	$V_{OH(D)}$	VI=0V, STB=0V, RL=60Ω, Fig.1, Fig.2	2.9	3.4	4.5	
CANL dominant output voltage	$V_{OL(D)}$		0.8		1.5	
Bus recessive output voltage	$V_{O(R)}$	VI=3V, STB=0V, RL=60Ω, Fig.1, Fig.2	2	2.5	3	V
Bus dominant differential output voltage	$V_{OD(D)}$	VI=0V, STB=0V, RL=60Ω, Fig.1, Fig.2	1.5		3	V
Bus recessive differential output voltage	$V_{OD(R)}$	VI=3V, S=0V, Fig.1, Fig.2	-0.012		0.012	V
		VI=3V, STB=0V, NO LOAD	-0. 5		0.05	V
Transmitter dominant voltage symmetry	$V_{dom(TX)sym}$	$V_{dom(TX)sym}=V_{CC}-V_{CANH}-V_{CANL}$	-400		400	mV
Transmitter voltage symmetry	V_{TXsym}	$V_{TXsym}=V_{CANH}+V_{CANL}$	$0.9V_{CC}$		$1.1V_{CC}$	V
Common-mode output voltage	V_{OC}	STB=0V, Fig.8	2	2.5	3	V
Peak-to-peak Common-mode output voltage	$\triangle V_{OC}$			30		mV
Short-circuit output current	I_{OS}	CANH=-12V, CANL=open, Fig.11	-105	-72		mA
		CANH=12V, CANL=open, Fig.11		0.36	1	
		CANL=-12V, CANH=open, Fig.11	-1	0.5		
		CANL=12V, CANH=open, Fig.11		71	105	
Recessive output current	$I_{O(R)}$	-27V<CANH<32V 0<VCC<5.25V	-2.0		2.5	mA

（V_{CC}=5V±10% and Temp=T_{MIN}~T_{MAX} unless specified otherwise; typical in V_{CC}=+5V and Temp=25℃）

DRIVER SWITCHING CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Propagation delay time,low-to-high-level output	tPLH	STB=0V, Fig.4	25	65	120	ns
Propagation delay time,low-to-high-level output	tPHL		25	45	90	ns
Differential output signal rise time	tr			25		ns
Differential output signal fall time	tf			50		ns
Enable time from standby mode to dominant	t_{EN}	Fig.7			10	μs
Bus dominant time-out time	t_{dom}	Fig.10	300	450	700	μs
Bus wake-up filter time	t_{BUS}		0.7		5	μs

（V_{CC}=5V±10% and Temp=T_{MIN}~T_{MAX} unless specified otherwise; typical in V_{CC}=+5V and Temp＝25℃）

RECEIVER ELECTRICAL CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Positive-going input threshold voltage	V_{IT+}	STB=0V, Fig.5		800	900	mV
Negative-going input threshold voltage	V_{IT-}		500	650		
Hysteresis voltage (VIT+ – VIT–)	V_{HYS}		100	125		
High-level output voltage	V_{OH}	IO=-2mA, Fig.6	4	4.6		V
Low-level output voltage	V_{OL}	IO=2mA, Fig.6		0.2	0.4	V
Power-off bus input current	$I_{(OFF)}$	CANH or CANL=5V, Other pin=0V			5	μA
Input capacitance to	C_I			13		pF

ground, (CANH or CANL)						
Differential input capacitance	C_{ID}			5		pF
Input resistance, (CANH or CANL)	R_{IN}	TXD=3V, STB=0V	15	30	40	KΩ
Differential input resistance	R_{ID}		30		80	KΩ
Input resistance matching	RI_{match}	CANH=CANL	-3%		3%	
The range of commen-mode voltage	V_{COM}		-12		12	V

（V_{CC}=5V±10% and Temp=T_{MIN}~T_{MAX} unless specified otherwise; typical in V_{CC}=+5V and Temp＝25℃）

RECEIVER SWITCHING CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Propagation delay time,low-to-high-level output	tPLH	STB=0V or VCC, Fig.6	60	100	130	ns
Propagation delay time,low-to-high-level output	tPHL		45	70	90	ns
RXD signal rise time	tr			8		ns
RXD signal fall time	tf			8		ns

（V_{CC}=5V±10% and Temp=T_{MIN}~T_{MAX} unless specified otherwise; typical in V_{CC}=+5V and Temp＝25℃）

DEVICE SWITCHING CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Loop delay1, driver input to receiver output, Recessive to Dominant	Td(LOOP1)	STB=0V，Fig.9	90		190	ns
Loop delay 2, driver input to receiver output, Dominant to Recessive	Td(LOOP2)		90		190	ns

（V_{CC}=5V±10% and Temp=T_{MIN}~T_{MAX} unless specified otherwise; typical in V_{CC}=+5V and Temp＝25℃）

OVER TEMPERATURE PROTECTION

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Shutdown junction temperature	Tj(sd)			160		℃

TXD-PIN CHARACTERISTICS

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
HIGH-level input current	I_{IH}(TXD)	VI=VCC	-2		2	μA
LOW-level input current	I_{IL}(TXD)	VI=0	-50		-10	μA
When VCC=0V，current on TXD pin	I_O(off)	VCC=0V，TXD=5V			1	μA
HIGH-level input voltage	V_{IH}		2		VCC+0.3	V
LOW-level input voltage	V_{IL}		-0.3		0.8	V
Open voltage on TXD pin	TXD_O		H			logic

（V_{CC}=5V±10% and Temp=T_{MIN}~T_{MAX} unless specified otherwise; typical in V_{CC}=+5V and Temp=25℃）

COMMOM-MODE STABILIZATION OUTPUT

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Common-mode stabilization output voltage	V_O	-500uA<I_o<500uA	0.3V_{CC}		0.7V_{CC}	V
Leakage current	$I_{O(stb)}$	STB=2, -12V<V_O<12V	-5		5	μA

（V_{CC}=5V±10% and Temp=T_{MIN}~T_{MAX} unless specified otherwise; typical in V_{CC}=+5V and Temp=25℃）

SUPPLY CURRENT

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Standby	I_{CC}	STB=VCC, V_I=VCC		5	12	μA
Dominant		V_I=0V, STB=0V, LOAD=60Ω		50	70	mA
Recessive		V_I=VCC, STB=0V, NO LOAD		6	10	mA

（V_{CC}=5V±10% and Temp=T_{MIN}~T_{MAX} unless specified otherwise; typical in V_{CC}=+5V and Temp＝25℃）

FUNCTION TABLE

Table1.CAN TRANSCEIVER TRUTH TABLE

V_{CC}	TXD(1)	STB(1)	CANH(1)	CANL(1)	BUS STATE	RXD(1)
4.5V~5.5V	L	L	H	L	Dominate	L
4.5V~5.5V	H or Open	X(1)	0.5V_{CC}	0.5V_{CC}	Recessive	H
4.5V~5.5V	X	H or Open	0.5V_{CC}	0.5V_{CC}	Recessive	H
0<V_{CC}<4.5V	X	X	0V<V_{CANH}<V_{CC}	0V<V_{CANL}<V_{CC}	Recessive	X

（1）H=high level; L=low level; X=irrelevant

Table 2. DRIVER FUNCTION TABLE

INPUTS		OUTPUTS		Bus State
TXD(1)	STB(1)	CANH(1)	CAL(1)	
L	L	H	L	Dominate
H or Open	X	Z	Z	Recessive
X	H or Open	Z	Z	Recessive

（1）H=high level; L=low level; X=irrelevant; Z=high impedance

Table 3. RECEIVER FUNCTION TABLE

V_{ID}=CANH-CANL	RXD(1)	Bus State(1)
V_{ID}≥0.9V	L	Dominate
0.5< V_{ID}<0.9V	?	?
V_{ID}≤0.5V	H	Recessive
Open	H	Recessive

（1）H=high-level; L=low-level; ?=uncertain

TEST CIRCUIT

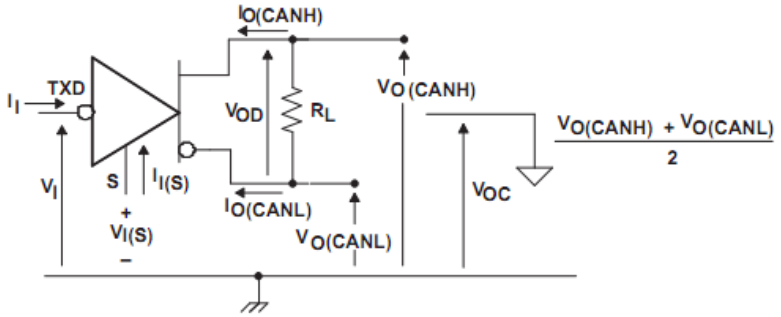


Fig.1 Driver Voltage, Current, and Test Definition

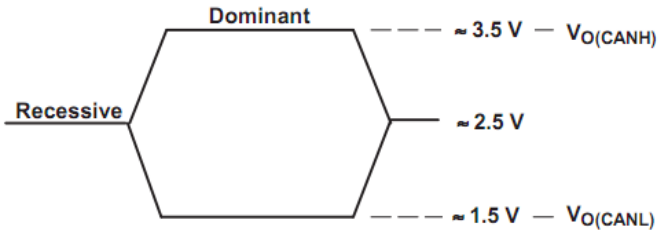


Fig.2 Bus Logic State Voltage Definition

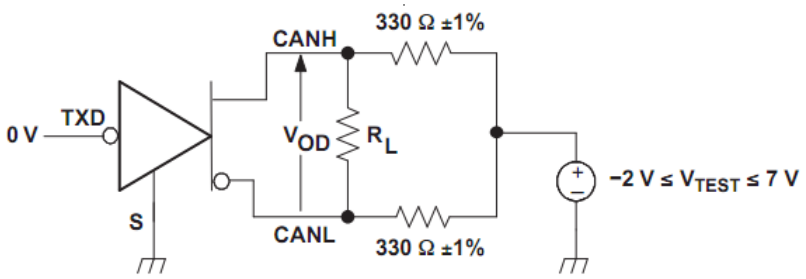


Fig.3 Driver V_{OD} Test Circuit

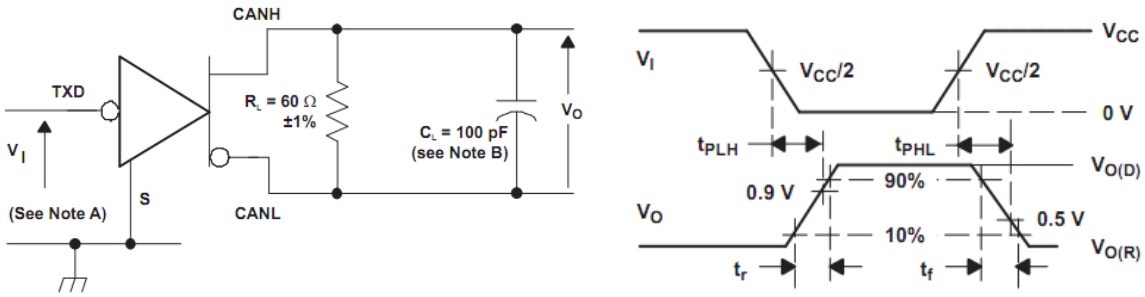


Fig.4 Driver Test Circuit and Waveform

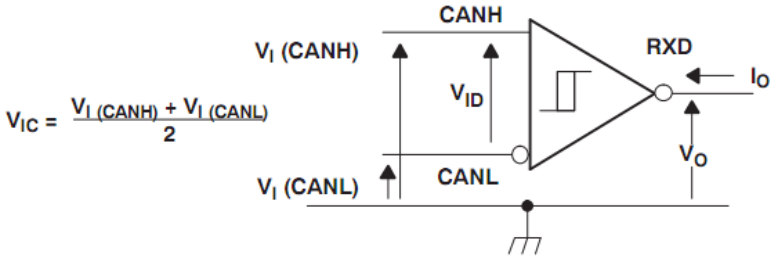
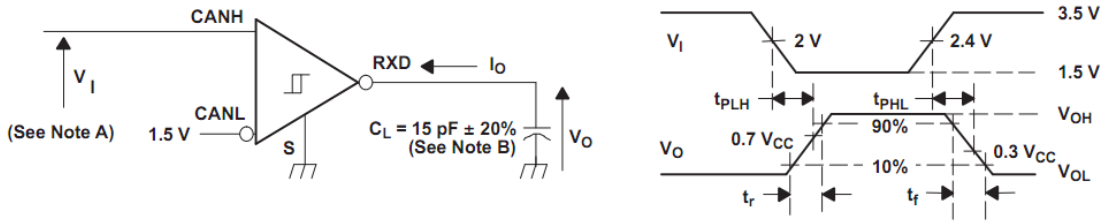


Fig.5 Receiver Voltage and Current Definition



A. The input pulse is supplied by a generator having the following characteristics: PRR ≤ 125 kHz, 50% duty cycle, t_r ≤ 6 ns, t_f ≤ 6ns, Z_O = 50 Ω.

B. C_L includes instrumentation and fixture capacitance within ±20%.

Fig.6 Receiver Test Circuit and Waveform

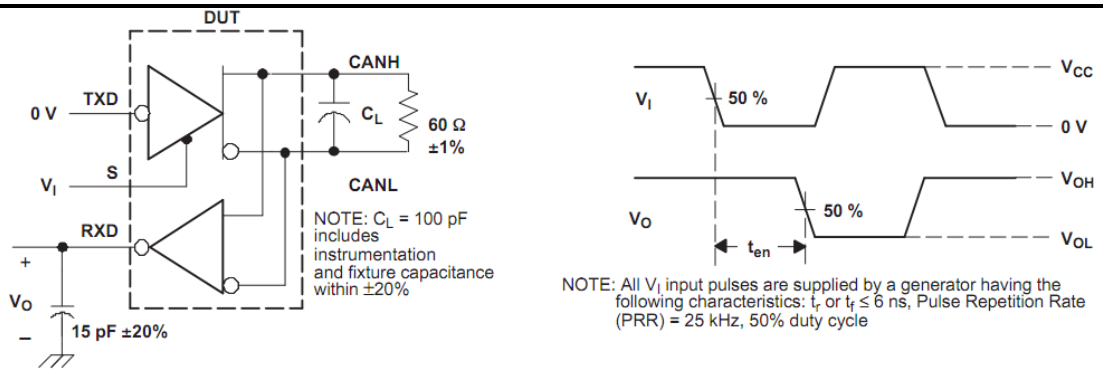
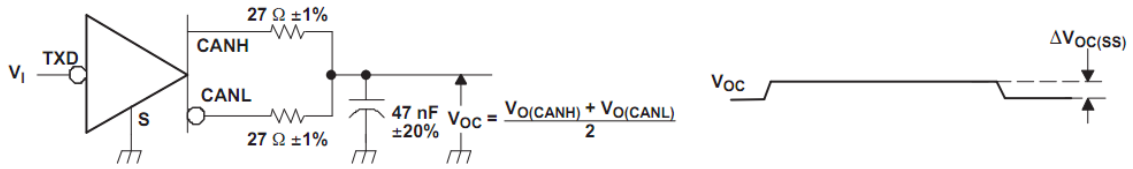


Fig.7 t_{EN} Test Circuit and Waveform



A. All VI input pulses are from 0 V to VCC and supplied by a generator having the following characteristics: tr or tf ≤ 6 ns. Pulse Repetition Rate (PRR) = 125 kHz, 50% duty cycle.

Fig.8 Peak-to-Peak Common Mode Output Voltage Test and Waveform

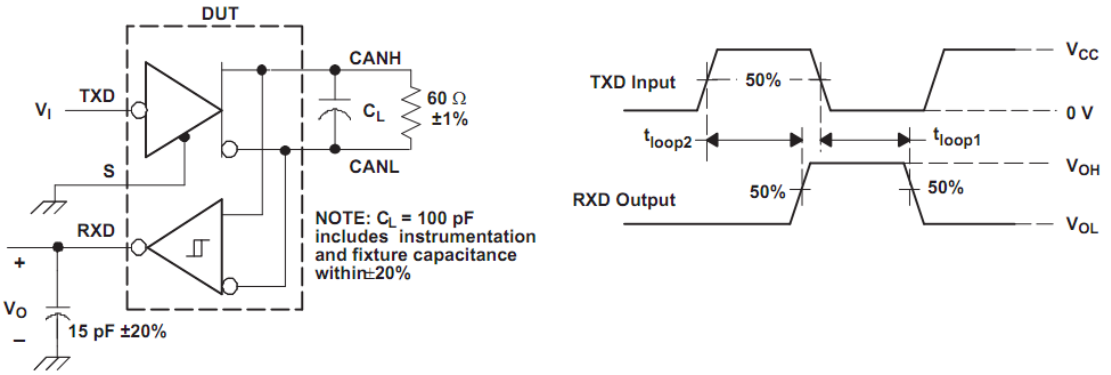


Fig.9 $t_{(LOOP)}$ Test Circuit and Waveform

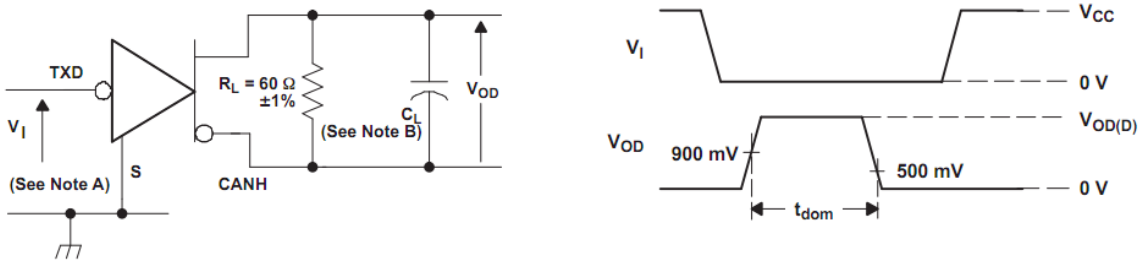


Fig.10 Dominant Time-Out Test Circuit and Waveform

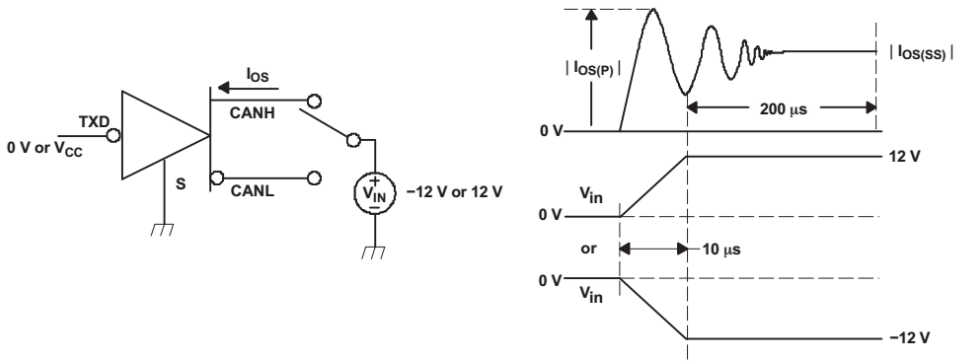


Fig.11 Driver Short-Circuit Current Test Circuit and Waveform

ADDIYIONAL DESCRIPTION

1 Sketch

The SIT1040 is the interface between the Controller Area Network (CAN) protocol controller and the physical bus, and can be applied to the fields of trucks, buses, cars, industrial control etc. It is primarily intended for high speed applications, up to 1 MBaud, in passenger cars. The device provides differential transmit capability to the bus and differential receive capability to the CAN controller, and fully compatible with the ISO 11898 standard.

2 Current protection

A current-limiting circuit protects the transmitter output stage from damage caused by accidental short-circuit to either positive or negative supply voltage, although power dissipation increases during this fault condition.

3 Fail-safe features

Pin TXD provides a pull-up towards VCC in order to force a recessive level in case pin TXD is unsupplied.
Pin STB provides a pull-up towards VCC in order to force the transceiver into standby mode in case pin STB is unsupplied.
In the event that the VCC is lost, pins TXD, STB and RXD will become floating to prevent reverse supplying conditions via these pins.

4 Over temperature protection

The output drivers are protected against over-temperature conditions. If the virtual junction temperature exceeds the shutdown junction temperature Tj(sd), the output drivers will be disabled until the virtual junction temperature becomes lower than Tj(sd) and TXD becomes recessive again.
By including the TXD condition, the occurrence of output driver oscillation due to temperature drifts is avoided.

5 TXD dominant time-out function

A ‘TXD dominant time-out’ timer circuit prevents the bus lines from being driven to a permanent dominant state(blocking all network communication) if pin TXD is forced permanently LOW by a hardware and/or software application failure. The timer is triggered by a negative edge on pin TXD.
If the duration of the LOW level on pin TXD exceeds the internal timer value (tdom), the transmitter is disabled, driving the bus lines into a recessive state. The timer is reset by a positive edge on pin TXD.

6 Operating modes

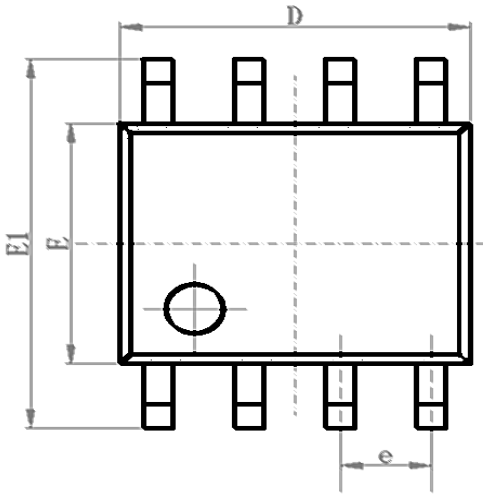
The SIT1040 provides two modes of operation which are selectable via pin STB:
High-speed mode and standby mode.
High-speed mode is normal working mode, by connecting STB to ground to set the SIT1040 to high-speed mode. In this mode the transceiver is able to transmit and receive data via the bus lines CANH and CANL. The differential receiver converts the analog data on the bus lines into digital data which is output to pin RXD via the multiplexer (MUX).

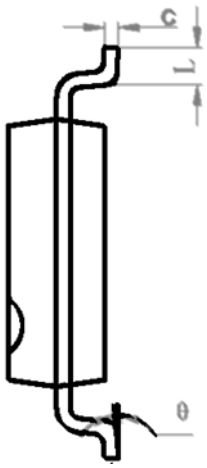
If a logic-high or open is applied to STB, the SIT1040 enters a low-current standby mode. In this mode the transmitter and receiver are switched off, and the low-power differential receiver will monitor the bus lines. A HIGH level on pin STB activates this low-power receiver and the wake-up filter, and after tBUS the state of the CAN bus is reflected on pin RXD.

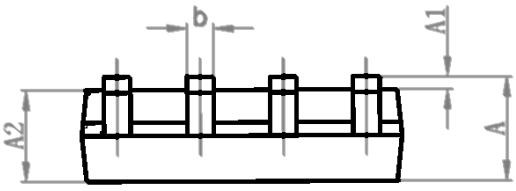
SOP8 DIMENSIONS

PACKAGE SIZE

SYMBOL	MIN./mm	TYP./mm	MAX./mm
A	1.50	1.60	1.70
A1	0.1	0.15	0.2
A2	1.35	1.45	1.55
b	0.355	0.400	0.455
D	4.800	4.900	5.00
E	3.780	3.880	3.980
E1	5.800	6.000	6.200
e		1.270BSC	
L	0.40	0.60	0.80
c	0.153	0.203	0.253
θ	-2°	-4°	-6°



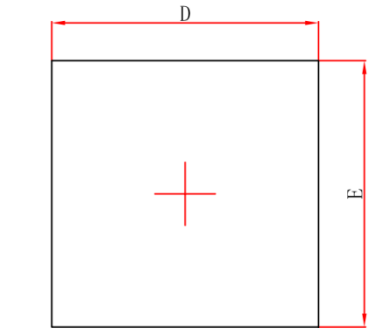


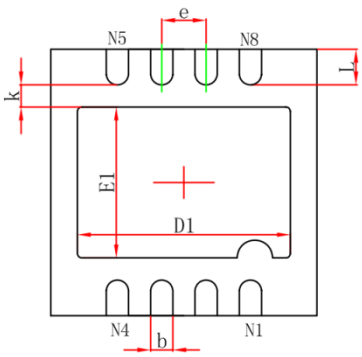


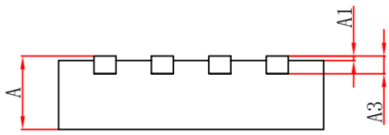
DFN3*3-8 /HVSON8 DIMENSIONS

PACKAGE SIZE

SYMBOL	MIN/mm	TYP /mm	MAX/mm
A	0.700		0.900
A1	0.000	0.02	0.050
A3		0.203 REF	
D	2.900	3.000	3.100
E	2.900	3.000	3.100
D1	1.400	1.5	1.600
E1	2.200	2.3	2.400
k		0.275 REF	
b	0.2	0.25	0.33
e		0.650 TYP	
L	0.250		0.575







ORDERING INFORMATION

TYPE NUMBER	TEMPERATURE	PACKAGE
SIT1040T	-40℃~125℃	SOP8
SIT1040TK	-40℃~125℃	HVSON8 / DFN3*3-8，Small Outline，Leadless

SOP8 tape packaging is 2500 pieces/disc. DFN tape packaging is 2500 pieces/disc.